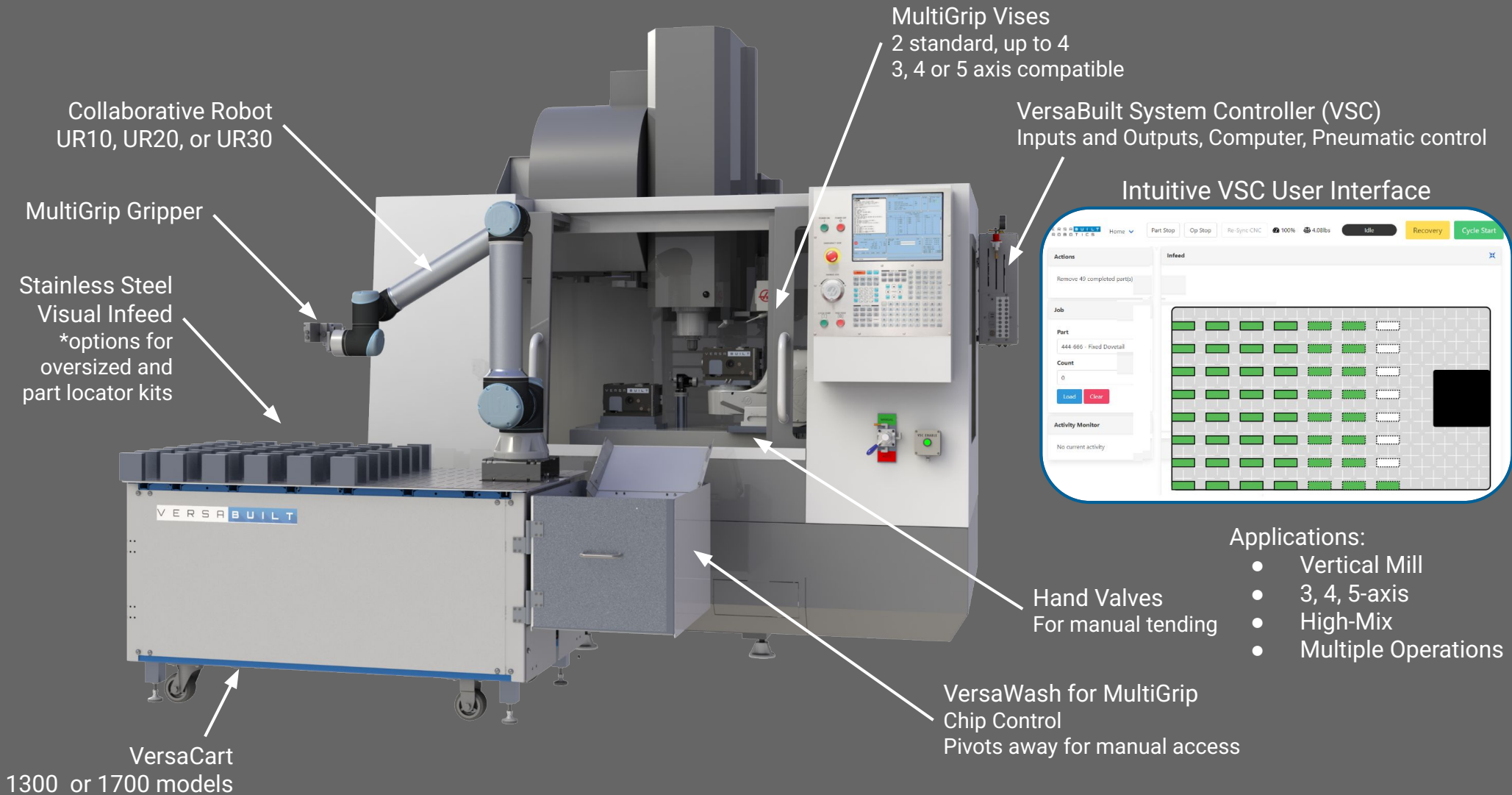


VERSABUILT

Mill Automation System with MultiGrip w/ UR



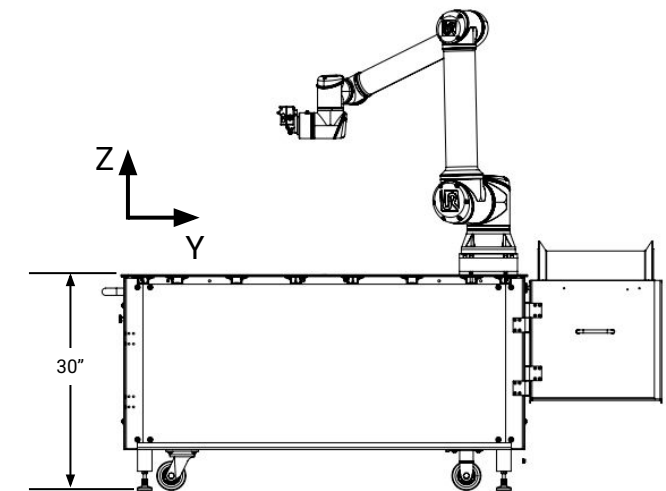
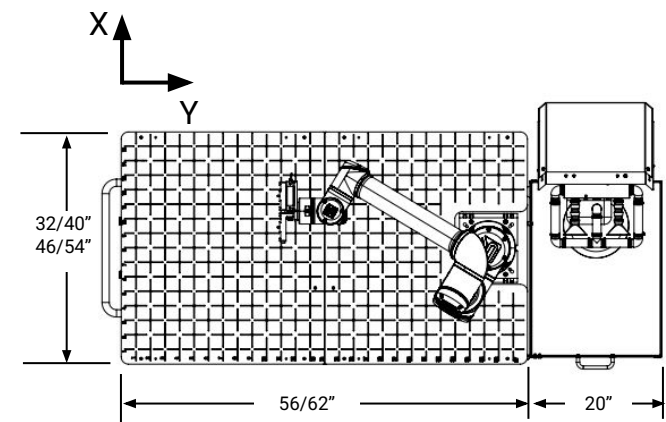
No Robot Programming

Install in 1-2 days

Plug and Play with any CNC

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Hardware/Software included <i>*Robots can be sold separately or system can use existing robots</i>	UR10e, UR 20 or UR30	MultiGrip Gripper	VersaWash for chip mitigation
	Robot2CNC communication	QTY: 2 MultiGrip Vises	Electrical signal and communication cables
	VersaBuilt System Controller (VSC)	MultiGrip Jaws for initial 1 to 2 parts	Pneumatic valves and tubing
	VSC User Interface Software	VersaCart 1300 with Standard SS Visual Infeed	Hand valves for Manual Tending
Vise Options	MultiGrip 2000, MultiGrip 4000, Standard Housing or Housing with Steel Top		
Maximum Part Sizes	Max Width x Length x Height	12 x 16 x 10 inches	
Maximum Payload Gripper = 1.70kg / 3.75lbs	Robot Model	Max Payload for Part + Gripper	
	UR10e	12.5kg / 27.5 lbs	
	UR20	20kg / 44.0 lbs	
	UR30	30kg / 66.0 lbs	
Software	VSC Software enables users to run system, recover, add/configure multiple parts, configure settings, test I/O, calibrate, and enable remote support.		
Programming	No Robot Programming required when used with VersaBuilt System Controller VSC configured software. New parts are added through Configuration of Jaws (OD/ID), and Parts (1 Op and 2Op processes standard), with parameter entry and checkbox selection for each type of process (1 Op w/ 1 Vise, 1 Op w/ 2-Vises, 2Op w/ 2-Vises)		
User Interface	User Interface Connection Options <i>*customer provided</i> • Web based application, connected via Wi-Fi or network, Phone, Tablet, Laptop or Computer • Monitor, keyboard, mouse connection to VersaBuilt System Controller		
Support	Remote connectivity available for software updates and remote support *Availability of network connection for remote support is customer responsibility		
CNC compatibility	Vertical Machining Centers *Horizontal Milling Centers, depending on layout Robot2CNC dynamic communication for Haas NGC/Legacy and Fanuc Focus 2.0 controls Handshake communication with all other CNC Controls (Cycle Start to CNC; Cycle End from CNC)		
Air Requirements	90-120 psi, 15-20 scfm *air should be conditioned to meet ISO 8573-1:2010 [7:4:4] standard		
Electrical Requirements	120VAC 1 Phase, 50/60Hz, Full Load 30A (Robot, VSC, Ethernet Switch, Router, VersaWash Pump)		
Options and Substitutions	VersaDoor CNC AutoDoor	Area Safety Scanners	Oversized SS Visual Infeed
	MultiGrip Jaw Options (OD, ID, Pallet)	VersaBites/VersaRails	Vise Pressure Doubler
	VersaCart Custom Infeed Kit	Extra Vise Valves up to 4 vises	VersaCart 1700
	Dual CNC Setup	VersaCart Anchor Kit	



MultiGrip™

- Pick and Place Parts with Jaws
- Flip parts without custom regrip
- Enables Multi-Operation parts
- Enables High-Mix

VERSABUILT

Robot2CNC Communication	Infeed Options available with System
1. Macro-Driver Communication with CNC	Standard > Single Layer of parts, aligned with the VersaCart Visual Infeed
Available for Haas Legacy, Haas NGC, and Fanuc Focus 2.0 controls (see list in VSC/CNC Manual)	Stacked > Option allowing for stacked parts with Outfeed placement on VersaCart or Bin Drop.
With CNC Dispatcher in memory, CNC programs are communicated via macro-variables from the VSC to the CNC to select programs from the CNC program list, then run as sub-routines in the Dispatcher.	Standard Stacked divides the VersaCart in half, one half for infeed, the other for outfeed.
CNC Cycle Start is initiated with a 2-wire relay connection to the CNC Cycle Start Button	Stacked Infeed, with Bin-Drop selected in the part configuration, doubles infeed w/out requirement of restacking the parts on the cart.
Cycle End is commanded at the end of the program through the dispatcher and M-code command.	Custom Infeed > Single Layer of parts, defined by the location of the first part position relative to the cart X/Y datums, then row/column spacing and quantities
G-Code Commands are available for control of Vise Open, Close, and Pressure Exhaust	Devices:
2. Standard-Driver Communication with CNC	MultiGrip Gripper - Pneumatic Gripper w/ interface for picking MultiGrip Jaws
Generalized handshake between VSC and CNC, for CNC Controls without Macro-Driver option	MultiGrip Vise - Pneumatic Vise w/ interface for securing MultiGrip Jaws
CNC Cycle Start is initiated with a 2-wire relay connection to the CNC Cycle Start Button	VersaCart - Steel construction on casters, with adjustable foot pads to lock position, robot pedestal and infeed options optimized for 1300mm and 1700mm reach robots
Cycle End is commanded at the end of the program through an M-code command triggering a 24VDC signal to the VSC.	VSC - Computer, Pneumatics, and Electrical Signal devices for System
*Alternative options for Cycle Start/Cycle End are available, such as push-button actuator for cycle start, and stack-light trigger for Cycle End, etc.	VersaWash - Chip Mitigation solution for MultiGrip processing, with a welded bucket mounted on hinges on the VersaCart, a recirculating pump with protective filter bag and basket, and adjustable nozzles for optimal wash of jaws.
	VSC Enable Button - Physical button, local to system, allowing for user access to VSC software
	MultiGrip Calibration Jaws - 1-piece MultiGrip Jaw, used for calibration of VersaCart and MultiGrip Vises

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VSC M8 Cable Digital Inputs and Outputs:	VSC Pneumatics:	VSC Accessories:
1. 24VDC Outputs	1. VSC Connections (push-to-connect)	1. Pneumatics
Cycle Start	Vise 1 Open	Supply, Shut-off and Lockout Valve
VersaWash	Vise 1 Close	Supply Air Pressure Gauge
Robot Lock (for Dual CNC tending applications)	Vise 2 Open	Vise Air Pressure Gauge
Pallet Ready (for CNC's with Pallet Ready button)	Vise 2 Close	Exhaust through bottom ports with push-to-connect fittings for customer routing, if desired
Door Interlock Release (for CNC's with Door Interlock Release button)	VersaDoor Open	
Chuck 1 Toggle (for lathe foot pedal)	VersaDoor Close	
Chuck 2 Toggle (for lathe foot pedal)	VersaBlast (air pilot signal)	
	2. UR Robot Controller connections	2. Electrical/User Interface:
2. 24VDC Inputs	Gripper 1 Open	110 VAC to 24VDC Power Supply with connector
Vise 1 and Vise 2 Sensors	Gripper 1 Close	HDMI for monitor connection to user-interface computer
VersaDoor 1 Open/Close Sensor	Gripper 2 Open	2x USB for software backup and connection to user-interface computer
VersaDoor 2 Open/Close Sensor	Gripper 2 Close	
VSC Enable		3. Networking:
CNC Cycle End (for non-macro-driver CNC controls)	3. Hand Valves	5-Port Ethernet Switch
Robot Lock (for Dual CNC tending applications)	Diverter Valve to switch between "Auto" / VSC valves or "Manual" Vise valves	Ethernet Cables for CNC, Robot Controller, Router, and VSC
Pallet Safe (for CNC's with Pallet Ready button)	2x Vise Hand Valves	WiFi or Networking Options available for U/I and Remote Support

VERSABUILT

Processes included with Mill Automation System w/ MultiGrip

1 Op w/ 1 Vise & 1 Jaw

1 Op w/ 2 Vises & 2 Jaws (pipeline)

2 Op w/ 2 Vises & 2 Jaws (1 jaw per operation)

*custom processes available for quotation, such as:

- 2 Op w/ 2 Vises & 1 Jaw (e.g., 3-axis + 4th axis)
- 3 Op w/ 3 Vises
- 2 Op w/ 4 Vises (2Op per 2 Vises on pallet changer)

CNC Programs for System Operation

Dispatcher Files (9000's)

*if 9000 programs are in use, file numbers can be changed

Example Table Load Program (8000)

*position the CNC table at the vise calibration location for robot load/unload operations

Example Table Wash Program (8001)

*chip mitigation between operations

Jaw Configuration

Jaw Type:
OD (outer diameter clamping)
ID (inner diameter clamping)

Jaw Weight

Jaw Name and Description (used when selecting Jaws in Part configuration)

General Part Configuration Data Entry

Part Number

Part Description

Process (1Op, 1 Op Pipeline, 2Op)

Part Width/Length/Diameter/Height, Weight at part states:

- Raw
- Op1 Complete
- Op2 Complete (2 Op process only)

Pick Heights

- Pick from infeed
- Place height

CNC Programs*

- Op1
- Op2 (2 Op process only)
- CNC Vise Wash Program
- CNC Table Load Program

Section of Jaws for each operation

Part Configuration Selections and Options:

Part Picking Options:

- Enable Part Find on Pick
- Clap Gripper on Pick
- Robot Settle
- Vise Settle
- Custom Infeed Spacing

Op1 Options:

- Vise Number (1 or 2 for 2-Vise setup)
- Y-Push (pick part with a Y-offset, push part with gripper after load in CNC to nominal center position)
- Vise Settle

Part Transfer Options (2Op process):

- Pick at transfer from Op1 to Op2
- Enable Part Find on Transfer
- Custom calibration position for Transfer
- CNC Vise wash after Op Transfer
- CNC Wash program after Op Transfer
- X/Y Transfer Pick Offsets

Op2 Options (2Op process):

- Robot Settle
- Vise Settle

Place Options

- Enable Part Find on Place
- Clap Gripper on Place
- Bin Drop (calibrated position at or near VersaWash)
- X/Y Place Offsets

Jaw Cleaning & VersaWash Options:

- Timing of Jaw Cleaning
- Dump Coolant
- VersaWash # of Cycles/Speed, and Drip Time/Speed

VERSA BUILT

Standard Systems:

VersaBuilt Automation Systems are Pre-programmed, Standardized CNC Machine Tending solutions with the robot moving between “Home” locations above the Table (Table Home), in front of the CNC (CNC Home), inside the CNC (InCNC Home), and performing options with the Gripper, Vises, VersaWash, and VersaDoor, based on the selected Part Configuration Selections/Options and setup on the VSC User-Interface Settings page. These Standard Systems are pre-programmed in a generalized manner for an easy-to-use interface, incorporating known CNC process requirements.

General MultiGrip Process Overview:

- CNC Dispatcher or Non-Macro Driver program is in memory
- User selects Part, Enters Quantity on VSC User Interface
- Operator loads parts on VersaCart, matching display on User Interface
- Operator loads MultiGrip Jaws for selected Part on Part Configuration defined Vise
- User selects Cycle Start on VSC user interface
- Robot Unloads MultiGrip Jaws from MultiGrip Vise with MultiGrip Gripper
- Robot Picks Part with Jaws
- Robot Loads Part and Jaws into Vise
- CNC Cycle Start / Machining Op1
- For 2Op Parts - Robot Transfers/Flips Part from Op1 to Op2 with Op2 Jaws picking Part from Op1 Jaws, then Unloads empty Op1 Jaws, then CNC Cycle Start / Machining Op2. After machining Op2, Robot Loads next Part with Op1 Jaws.
- Robot Unloads Finished Part and Jaws
- After Unload of Finished Part, the Part is Placed back at VersaCart Infeed location or Bin-Dropped
- Jaws are washed per Part Configuration Selections
 - VersaWash pumps water only and does not include an air knife - Parts and Jaws drip dry.
- CNC Programs are run sequentially one-operation at a time
- Parts can be added to the system while it is running a job, either by adding parts to empty slots shown on the User Interface, or Operator unloading of finished parts and adding on the User Interface.

General System Notes:

- The user interfacing device is provided by the customer (not included in the quoted price). The user interface options are:
 - Wi-Fi connected device with Web-Browser (e.g., laptop, tablet) connected to the VSC interface via a Wi-Fi signal from the VSC router
 - Ethernet connectivity from device with Web-Browser connected to the VSC interface via VSC Ethernet Switch
 - Monitor/Keyboard/Mouse connected directly to the VSC via HDMI and USB ports
- The system operates on software local to the system (i.e., an internet connection is not required for the system to run).
- Pneumatic Tubing is color coded for applications. In general, Red or Black = Close, Blue or White/Clear = Open.
- Compressed air supply shall be 80 to 115 psi and conditioned to meet ISO 8573-1:2010 [7:4:4] standard. Maximum system air consumption is 15-20 SCFM.
- Remote Support is critical for success for installation, troubleshooting and software updates.
- Terms and conditions of sale can be found on the VersaBuilt website: www.versabuilt.com

Definitions:

- **Settle** - Gripper Open/Close or Gripper Float to seat the part in Z, with options for seating in Y
- **Float** - 24VDC Signals to Valves are turned off, allowing Grippers and VersaDoors to move freely
- **Clap** - Open and close the gripper multiple times during part pick and part place
- **Part Find** - Use of robot force-feedback to detect part or surface
- **FreeDrive** - Robot state where an operator can freely move the robot by gently pushing on the robot joints
- **Bin Drop** - Option for placing or dropping a part at a calibrated location (in location behind robot base, near the VersaWash tank), rather than placing the finished part back on the VersaCart Infeed.
- **Pipeline** - Optimized sequence of part processing where a 1Op part is processed in 2 different vises, i.e., first part in Vise 1 with Jaw 1, second part in Vise 2 with Jaw 2, third part in Vise 1 with Jaw 1. Pipelining is the most efficient process for 1 Op parts with MultiGrip.
- **Dump coolant** - after Jaw unload from the Vise, flipping the jaws to drip coolant in the CNC or on the VersaWash bucket