

VERSABUILT

Mill Automation System with DuoGrip and UR

Collaborative Robot
UR10, UR20, or UR30

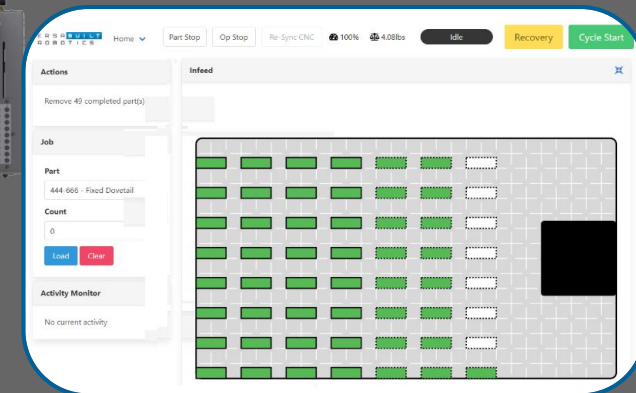
DuoGrip Gripper
w/ VersaBlast wrist air
DuoGrip 400 or DuoGrip 2000

Stainless Steel
Visual Infeed
*options for
oversized and
part locator kits

*Vises sold separately

VersaBuilt System Controller (VSC)
Inputs and Outputs, Computer, Pneumatic control

Intuitive VSC User Interface



Hand Valves
For manual tending

*VersaWash sold separately

*Regrip Station for 2 Operation Parts
sold separately

Applications:

- Horizontal Mill
- Vertical Mill
- 3, 4, 5-axis
- 1Op, Multi-Op with Regrip

VersaCart
1300 or 1700 models

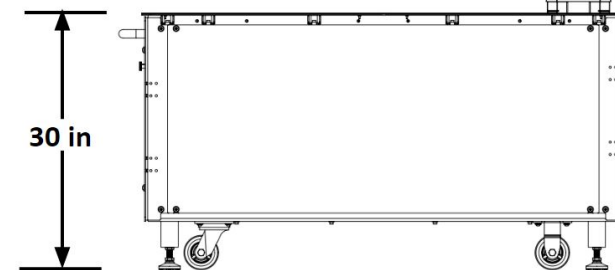
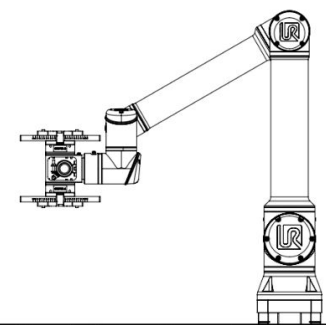
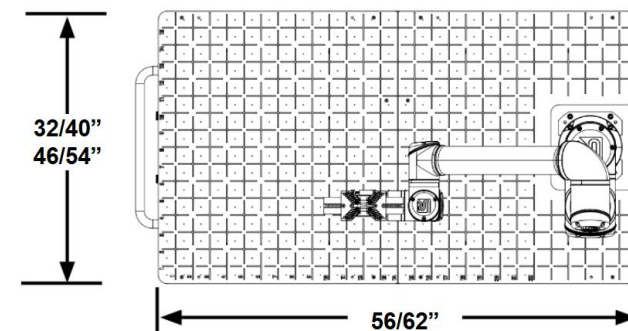
No Robot Programming

Install in 1-2 days

Plug and Play with any CNC

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Hardware/Software included <i>*Robots can be sold separately or system can use existing robots</i>	UR10e, UR 20 or UR30	DuoGrip Gripper w/ VersaBlast	Electrical signal and communication cables
	Robot to CNC communication	VersaCart 1300 with Standard SS Visual Infeed	Pneumatic valves and tubing
	VersaBuilt System Controller	VSC User Interface Software	Hand valves for Manual Tending
Vise Options	3rd Party Vises MultiGrip 2000, MultiGrip 4000, Standard Housing or Housing with Steel Top		
Maximum Part Sizes	Max Width x Length x Height	8.25 inch Diameter With provisions for larger round and rectangular sizes	
Maximum Payload Gripper weights: DuoGrip 400 = 3.6 kg DuoGrip 2000 = 6.0 kg	Robot Model	Max Payload for Part + Gripper	
	UR10e	12.5kg / 27.5 lbs	
	UR20	20kg / 44.0 lbs	
	UR30	30kg / 66.0 lbs	
Max Gripping Capacity	DuoGrip 400 = 9 lbs per gripper (200 N clamping force at 101 psi) DuoGrip 2000 = 40 lbs per gripper (1000 N clapping force at 94 psi)		
Software	VSC Software enables users to run system, recover, add/configure multiple parts, configure settings, test I/O, calibrate, and enable remote support.		
Programming	No Robot Programming required when used with VersaBuilt System Controller VSC configured software		
User Interface	User Interface Connection Options <i>*customer provided</i> - Web based application, connected via Wi-Fi or network, Phone, Tablet, Laptop or Computer - Monitor, keyboard, mouse connection to VersaBuilt System Controller		
Support	Remote connectivity available for software updates and remote support <i>*availability of network connection for remote support is customer responsibility</i>		
CNC compatibility	Vertical Machining Centers *Horizontal Milling Centers, depending on layout Robot2CNC dynamic communication for Haas NGC/Legacy and Fanuc Focus 2.0 controls Handshake communication with all other CNCs		
Air Requirements	90-120 psi, 15-20 scfm *air should be conditioned to meet ISO 8573-1:2010 [7:4:4] standard		
Electrical Requirements	120VAC 1 Phase, 50/60Hz, Full Load 30A (Robot, Controls, VersaWash Pump)		
Options and Substitutions	VersaDoor CNC AutoDoor	Area Safety Scanners	Shaft Fingers and Shaft Infeed
	MultiGrip Vises	MultiGrip Jaws	Oversized SS Visual Infeed
	VersaCart Custom Infeed Kit	VersaBites/VersaRails	Vise Pressure Doubler
	VersaWash	VersaCart Anchor Kit	DuoGrip 2000



DuoGrip™

Double Headed Gripper
Flexible Hardware Options
2 sizes available:

DuoGrip 400
DuoGrip 2000

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Robot2CNC Communication	Infeed Options available with System
1. Macro-Driver Communication with CNC	Standard > Single Layer of parts, aligned with the VersaCart Visual Infeed
Available for Haas Legacy, Haas NGC, and Fanuc Focus 2.0 controls (see list in VSC/CNC Manual)	Stacked > Option allowing for stacked parts with Outfeed placement on VersaCart or Bin Drop.
With CNC Dispatcher in memory, CNC programs are communicated via macro-variables from the VSC to the CNC to select programs from the CNC program list, then run as sub-routines in the Dispatcher.	Standard Stacked divides the VersaCart in half, one half for infeed, the other for outfeed.
CNC Cycle Start is initiated with a 2-wire relay connection to the CNC Cycle Start Button	Stacked Infeed, with Bin-Drop selected in the part configuration, doubles infeed w/out requirement of restacking the parts on the cart.
Cycle End is commanded at the end of the program through the dispatcher and M-code command.	Custom Infeed > Single Layer of parts, defined by the location of the first part position relative to the cart X/Y datums, then row/column spacing and quantities
G-Code Commands are available for control of Vise Open, Close, and Pressure Exhaust	Devices/Hardware:
2. Standard-Driver Communication with CNC	DuoGrip Gripper - Double-Headed Pneumatic w/ Puck Picking and VersaBlast, and option for Shaft Picking. Gripper 1 Picks Parts and Loads Workholding; Gripper 2 Unloads from Workholding and Places Parts
Generalized handshake between VSC and CNC, for CNC Controls without Macro-Driver option	VersaCart - Steel construction on casters, with adjustable foot pads to lock position, robot pedestal and infeed options optimized for 1300mm and 1700mm reach robots
CNC Cycle Start is initiated with a 2-wire relay connection to the CNC Cycle Start Button	Shaft Infeed - Indeed accessory for positioning round shafts for processing with the DuoGrip Gripper with Shaft Fingers.
Cycle End is commanded at the end of the program through an M-code command triggering a 24VDC signal to the VSC.	VSC 2.0 - Computer, Pneumatics, and Electrical Signal devices for System
*Alternative options for Cycle Start/Cycle End are available, such as push-button actuator for cycle start, and stack-light trigger for Cycle End, etc.	VSC Enable Button - Physical button, local to system, allowing for user access to VSC software
	VersaBlast - Air amplifier for chip mitigation, blowing high-flow compressed air on Chuck. Controlled by air pilot valve in VSC to High-Flow valve external to the VSC, mounted on a plate with magnets for mounting.

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VSC M8 Cable Digital Inputs and Outputs:	VSC Pneumatics:	VSC Accessories:
1. 24VDC Outputs	1. VSC Connections (push-to-connect)	1. Pneumatics
Cycle Start	Vise 1 Open	Supply, Shut-off and Lockout Valve
VersaWash	Vise 1 Close	Supply Air Pressure Gauge
Robot Lock (for Dual CNC tending applications)	Vise 2 Open	Vise Air Pressure Gauge
Pallet Ready (for CNC's with Pallet Ready button)	Vise 2 Close	Exhaust through bottom ports with push-to-connect fittings for customer routing, if desired
Door Interlock Release (for CNC's with Door Interlock Release button)	VersaDoor Open	
Chuck 1 Toggle (for lathe foot pedal)	VersaDoor Close	
Chuck 2 Toggle (for lathe foot pedal)	VersaBlast (air pilot signal)	
	2. UR Robot Controller connections	2. Electrical/User Interface:
2. 24VDC Inputs	Gripper 1 Open	110 VAC to 24VDC Power Supply with connector
Vise 1 and Vise 2 Sensors	Gripper 1 Close	HDMI for monitor connection to user-interface computer
VersaDoor 1 Open/Close Sensor	Gripper 2 Open	2x USB for software backup and connection to user-interface computer
VersaDoor 2 Open/Close Sensor	Gripper 2 Close	
VSC Enable		3. Networking:
CNC Cycle End (for non-macro-driver CNC controls)	3. Hand Valves	5-Port Ethernet Switch
Robot Lock (for Dual CNC tending applications)	Diverter Valve to switch between "Auto" / VSC valves or "Manual" Vise valves	Ethernet Cables for CNC, Robot Controller, Router, and VSC
Pallet Safe (for CNC's with Pallet Ready button)	2x Vise Hand Valves	WiFi or Networking Options available for U/I and Remote Support

Processes included with Mill Automation System w/ DuoGrip

1Op w/ 1 Vise
 2Op w/ Regrip w/ 1 Vise
 2 Op w/ Regrip w/ 2 Vises (pipeline)
 Single Gripper Puck(for heavy parts)
 Single Gripper Shaft (for heavy parts)

Infeed Options:
 Standard Infeed (1300 and 1700 Cart)
 Stacked Infeed

*custom processes available for quotation

CNC Programs for System Operation

Dispatcher Files (9000's)
 *if 9000 programs are in use, file numbers can be changed

Example Table Load Program (8000)
 *position the CNC table at the vise calibration location for robot load/unload operations
 *For Mill Automation Systems

Example Table Wash Program (8001)
 *chip mitigation between operations

General Part Configuration Data Entry

Part Number

Part Description

Process (1Op, 2Op w/ Regrip, etc)

Part Diameter, Height, Weight at part states:

- Raw
- Op1 Complete
- Op2 Complete (2 Op process only)

Pick Heights

- Pick from infeed
- Place height

CNC Programs*

- Op1
- Op2 (2 Op process only)

Part Configuration Selections and Options:

Process:

- Bin Drop (calibrated position at or near VersaWash)
- Custom Infeed Spacing

Raw Material / Part Picking Options:

- OD Clamp or ID Pick
- Enable Part Find on Pick
- Float Robot on Pick
- Robot Settle (clamp or float)

Vise Calibration Options:

- Before Vise Load Datum Centering
- Pick Next Part on Datum Fail (part mispick)
- Part Specific Vise Calibration
- Distance from Vise to End of Part

Vise Load Options:

- Vise Number (1 or 2 for 2-Vise setup)
- Vise OD or ID Clamping
- Vise Clamp Direction (X or Y)
- Vise Load Clearance Distance
- X & Y Offsets
- Vise Settle
- Find Vise on Load
- Apply Force on Load
- Float Robot on Load

Vise Unload Options:

- X & Y Offsets
- Find Vise on Unload
- Regrip Options for 2 Op Parts

VersaBlast Options:

- VersaBlast Before / After Unload

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Standard Systems:

VersaBuilt Automation Systems are Pre-programmed, Standardized CNC Machine Tending solutions with the robot moving between “Home” locations above the Table (Table Home), in front of the CNC (CNC Home), inside the CNC (InCNC Home), and performing options with the Gripper, VersaBlast, Lathe Chucks, and VersaDoor, based on the selected Part Configuration Selections/Options and setup on the VSC User-Interface Settings page. These Standard Systems are pre-programmed in a generalized manner for an easy-to-use interface, incorporating known CNC process requirements.

General DuoGrip Lathe Process Overview:

- CNC Dispatcher or Non-Macro Driver program is in memory
- User selects Part, Enters Quantity on VSC User Interface
- Operator loads parts on VersaCart, matching display on User Interface
- Operator configures DuoGrip Gripper for selected Part
- User selects Cycle Start on VSC user interface
- Robot Picks part with Gripper 1
- Robot Loads Part Vise
- CNC Cycle Start / Op1
- For 2Op Parts - Robot Unloads Part with Gripper 2, places the Part on the Regrip Station, Picks the Part from the underside of the Regrip Station with Gripper 1, Loads the Part into the Chuck, then CNC Cycle Start / Op2.
- While the CNC is running, the Robot Picks the Next Part with Gripper 1.
- After CNC Operation is complete, Gripper 2 Unloads the Part, and Gripper 1 Loads the Next Part.
- The Chuck can be washed with a CNC wash and the Part Configuration includes options for using VersaBlast to clean the chuck, before and after Part Unload.
- CNC Programs are run sequentially one-operation at a time
- Parts can be added to the system while it is running a job, either by adding parts to empty slots shown on the User Interface, or Operator unloading of finished parts and adding on the User Interface.

General System Notes:

- The user interfacing device is provided by the customer (not included in the quoted price). The user interface options are:
 - Wi-Fi connected device with Web-Browser (e.g., laptop, tablet) connected to the VSC interface via a Wi-Fi signal from the VSC router
 - Ethernet connectivity from device with Web-Browser connected to the VSC interface via VSC Ethernet Switch
 - Monitor/Keyboard/Mouse connected directly to the VSC via HDMI and USB ports
- The system operates on software local to the system (i.e., an internet connection is not required for the system to run).
- Pneumatic Tubing is color coded for applications. In general, Red or Black = Close, Blue or White/Clear = Open.
- Compressed air supply shall be 80 to 115 psi and conditioned to meet ISO 8573-1:2010 [7:4:4] standard. Maximum system air consumption is 15-20 SCFM.
- Remote Support is critical for success for installation, troubleshooting and software updates.
- Terms and conditions of sale can be found on the VersaBuilt website: www.versabuilt.com

Definitions:

- **Settle** - Gripper Open/Close or Gripper Float to seat the part in Z
- **Float** - 24VDC Signals to Valves are turned off, allowing Grippers and VersaDoors to move freely
- **Clap** - Open and close the gripper multiple times during part pick and part place
- **Part Find** - Use of robot force-feedback to detect part or surface
- **FreeDrive** - Robot state where an operator can freely move the robot by gently pushing on the robot joints
- **Bin Drop** - Option for placing or dropping a part at a calibrated location (in location behind robot base, near the VersaWash tank), rather than placing the finished part back on the VersaCart Infeed.
- **Dump coolant** - after unload from the CNC, flipping the Gripper to drip coolant in the CNC or on the VersaWash bucket