

VERSABUILT ROBOTICS



Mill Automation Kit UR-10E Robot Installation, Configuration and Operation

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UR10e Robot Installation

Section 1

Install UR10e Robot onto VersaCart 1300

- Tools:

- 6mm hex key
- 13mm open-ended wrench

- Parts:

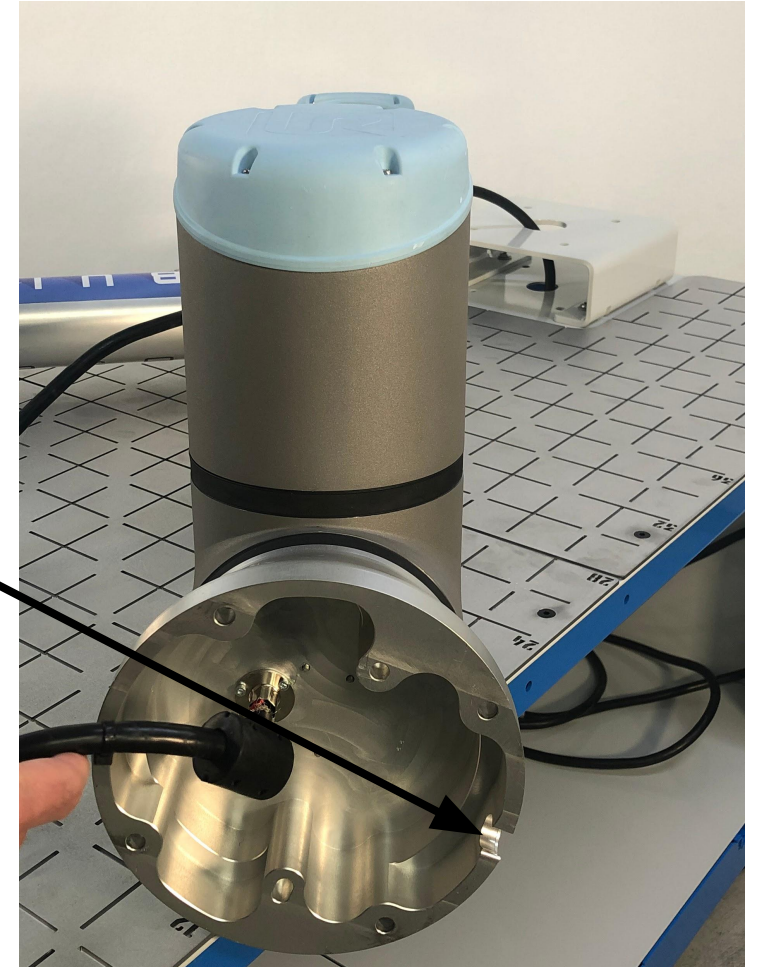
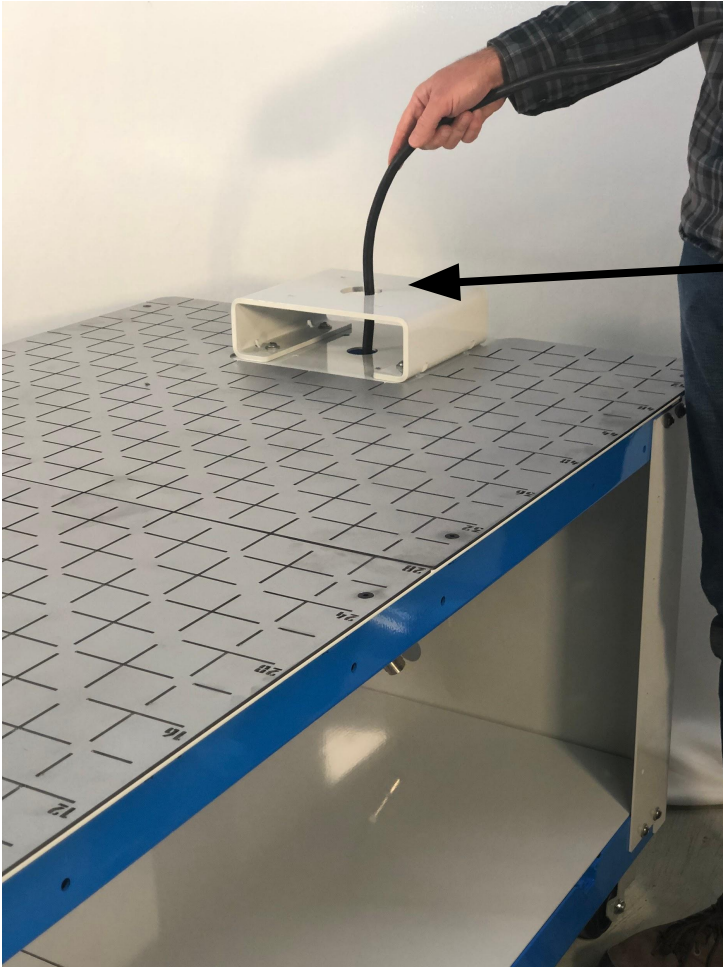
- UR10e Robot
- VersaCart 1300
- 4 x M8 Socket Head Screws x 30mm L
- 4 x M8 Hex Nuts



Route UR10e Cable

ROBOT POWER DISCONNECTED

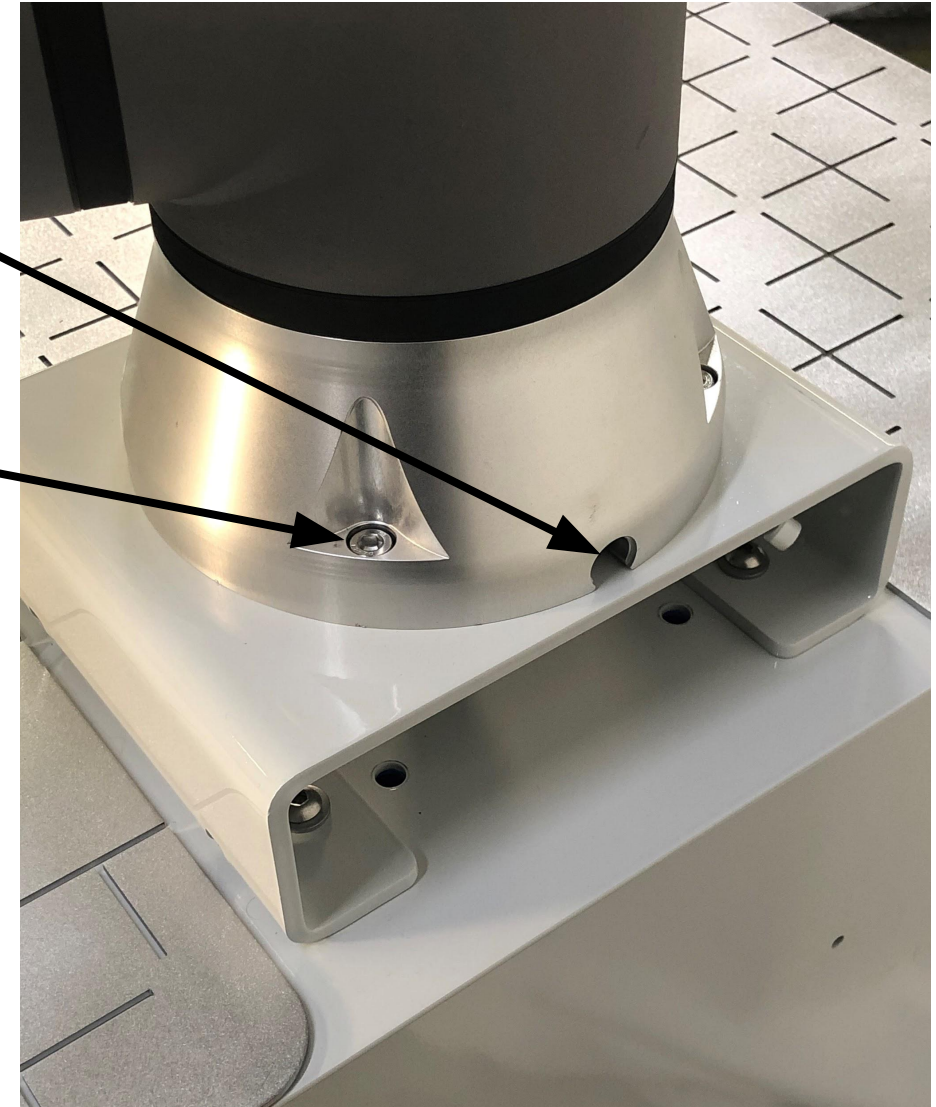
- Place robot on VersaCart table top
- Route robot cable through hole in VersaCart robot stand and table top
- Pull robot cable out of slot in robot base so the cable can pass through the bottom of the robot



Locate and Secure UR10e Robot on VersaCart 1300

- Position UR10e robot on VersaCart pedestal, with the robot's cable slot in the base positioned to the back of the VersaCart
- Secure the UR10e robot to the VersaCart robot pedestal with 4 x M8 Socket Head Screw x 30mm Length - Apply a small drop of medium strength threadlocker to each fastener

Note: *Screws are attached with captive hex nuts press-fit into the bottom side of the pedestal. If necessary, use a 13mm wrench on the captive hex nut while tighten screw into place.*



Route Teach Pendant Cable

- Tools:
 - Adjustable wrench
- Parts:
 - Controller
 - Teach Pendant

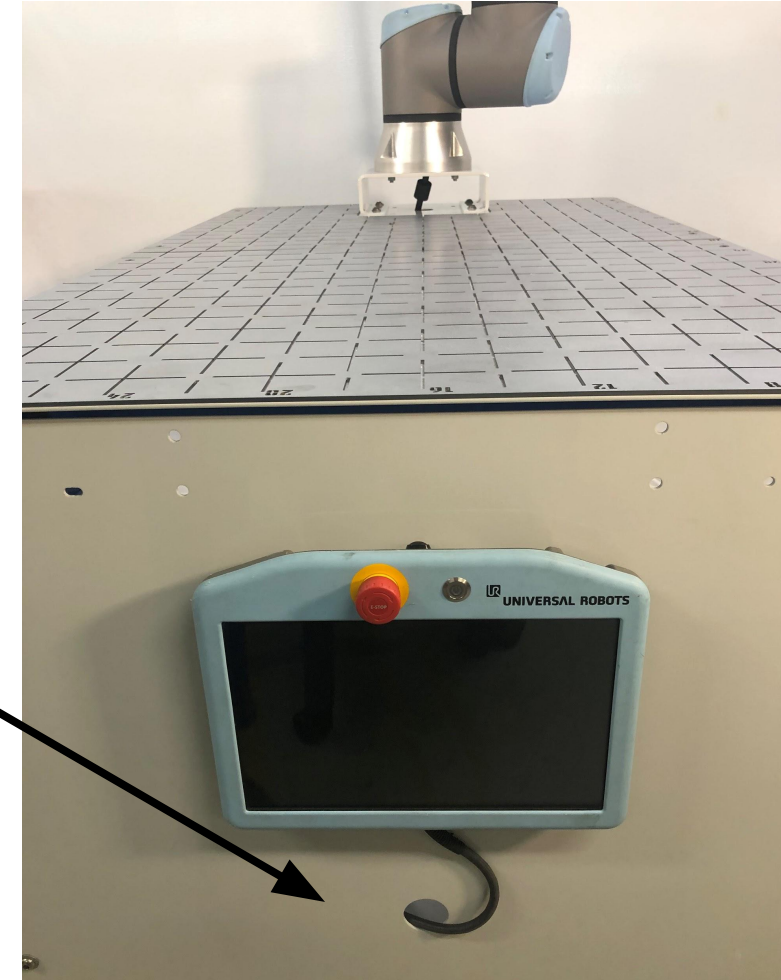
2 types of sheet metal are in use for the VersaCart. End panels with thru holes for routing the Teach Pendant cable and end panels with open slots. Thru hole end panels require disconnecting the cable inside the UR Controller, shown on the following page. Open slot end panels allow the teach pendant to be routed under the panel by removing a support plate behind the panel.



Route Teach Pendant Cable (thru hole end panel)

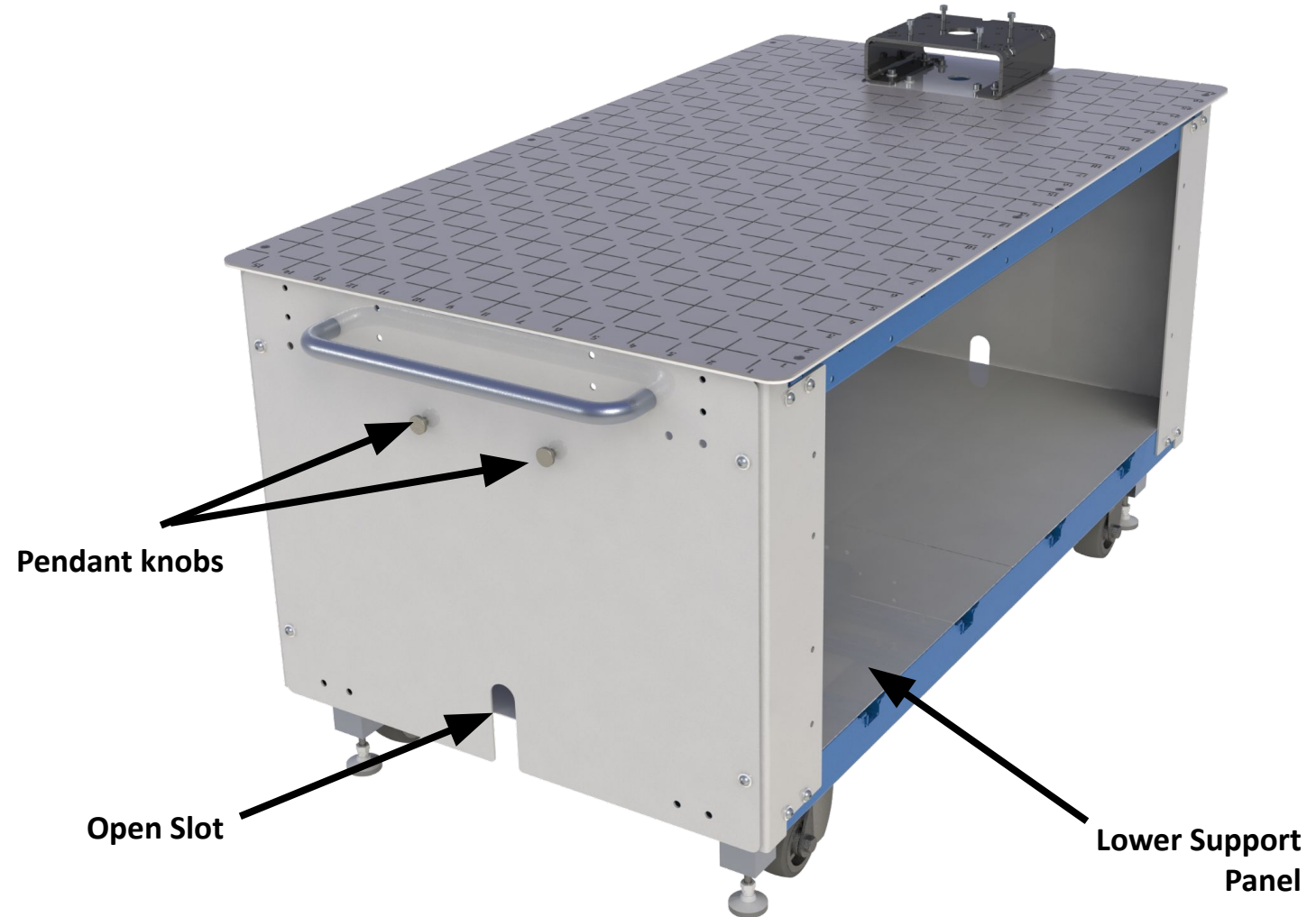


- Lay the controller on the top of the cart and open the access door
- Disconnect the teach pendant connector by pressing the sides and pulling down
- With adjustable wrench, loosen and remove the teach pendant bulkhead fitting at the bottom of the controller
- Route the teach pendant cable through the hole in the VersaCart and hang the teach pendant as shown
- Reinstall the teach pendant bulkhead fitting and plug in the teach pendant connector in the controller



Route Teach Pendant (open slot end panel)

- Lay the controller on the top of the cart
- Slide lower support panel, on opposite side of the robot pedestal, on top of the lower support panel under the robot pedestal
- Route Teach Pendant under end panel, and hang pendant on knobs
- Replace lower support panel and place controller on a lower support panel



Connect Robot Power and Signal Cables



- Attach the robot cable to the robot controller
- Position robot controller in the VersaCart underneath the robot as shown
- **Do not power-up the robot yet**



MultiGrip FJ Gripper Installation

Section 2

Install MultiGrip FJ Gripper

- Tools:

- 4mm hex key
- 5mm hex key
- 2 x Lineman's Pliers
- Side cutting pliers
- Medium Strength Threadlocker

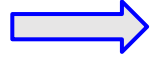
- Parts:

- MultiGrip FJ Gripper assembly
- 4 x M6x1.0 SHCS x 12mm L
- 1 x 15-foot length of Red 5/32" tubing
- 1 x 15-foot length of Blue 5/32" tubing
- 8 x 16" Long Cable Ties (Zip ties)



Install MultiGrip FJ Gripper

1. **Power up the robot** and position the end of arm in a convenient location for Gripper assembly



Base	+10°
Shoulder	-80°
Elbow	+90°
Wrist 1	-10°
Wrist 2	+90°
Wrist 3	-180°

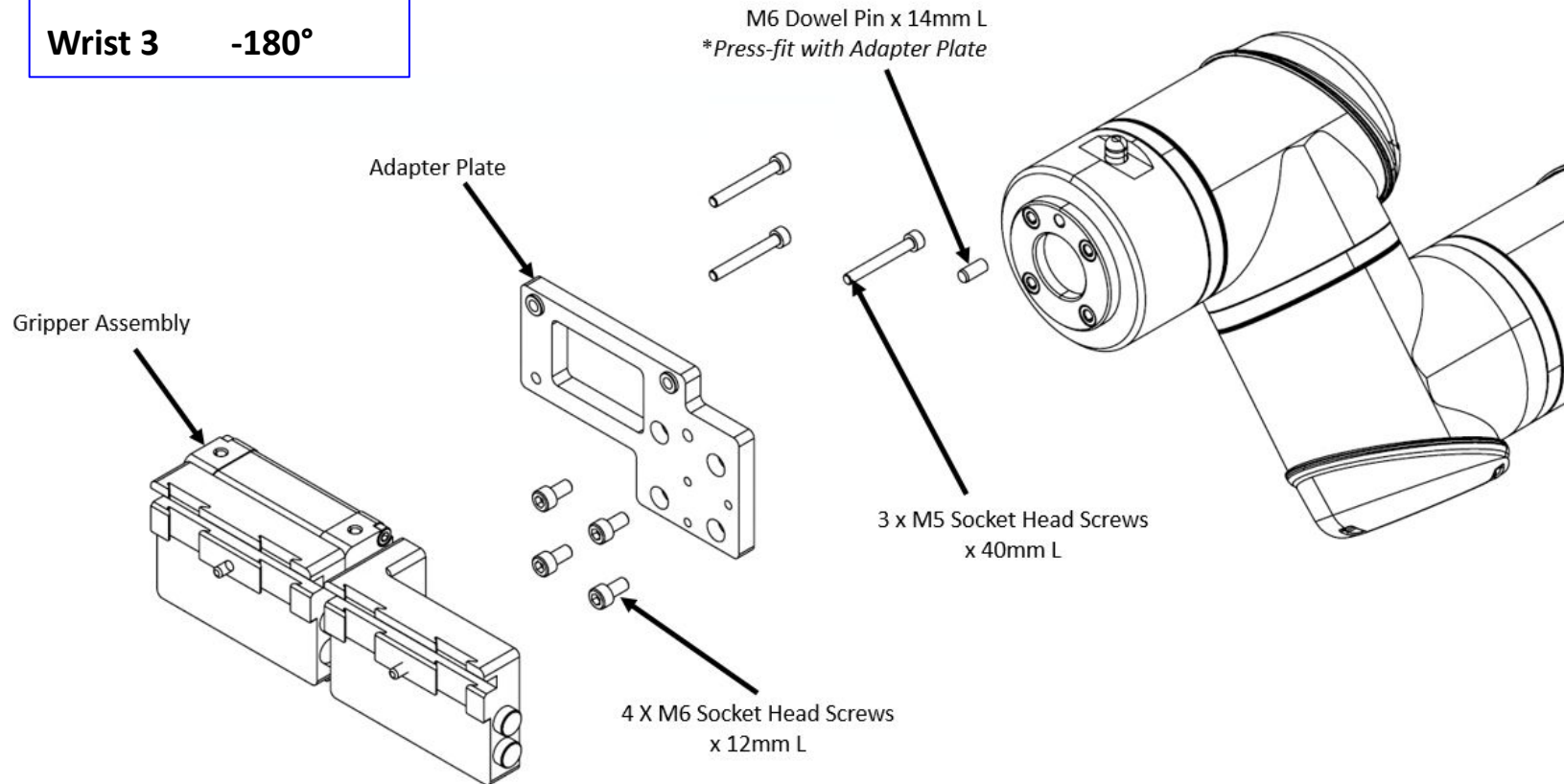
2. Place a small drop of thread locker onto each bolt in the MultiGrip FJ Gripper Fasteners package

3. Attach the Adapter Plate to the robot:

Align the Adapter Plate with the M6 dowel pin to mating features on the robot end of arm

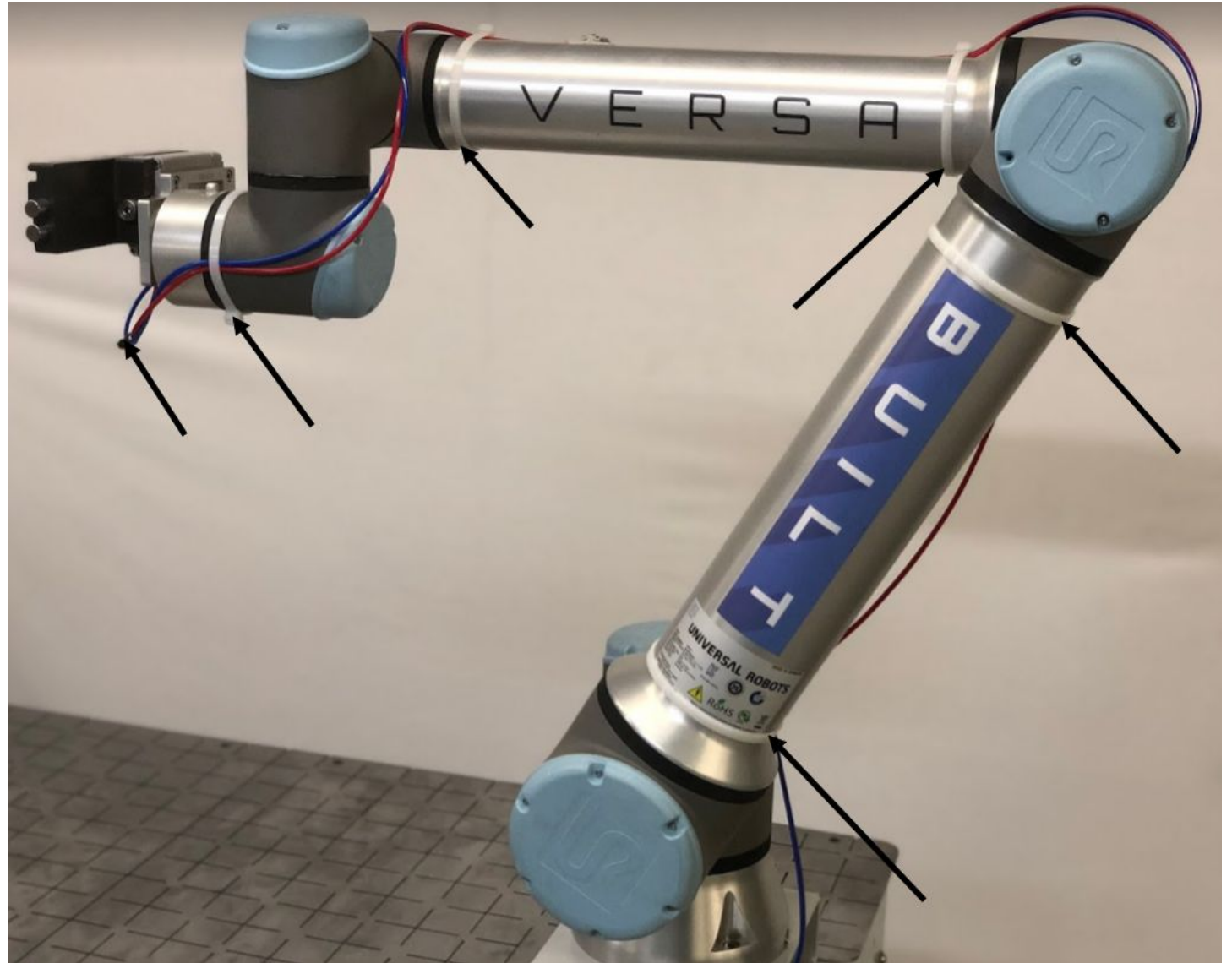
Secure the Adapter plate with 4 x M6 Socket Head Screws x 12mm L

4. Attach the Gripper Assembly to the Adapter Plate with 3 x M5 Socket Head Screws x 40mm L



Route MultiGrip FJ Gripper Air Lines

- Insert the Gripper Air Lines into the gripper air fittings as shown
 - Blue tubing is Gripper Open
 - Red tubing is Gripper Close
- Using 1 x 18" cable ties, loosely secure the airline on the lower and upper aluminum arms (*arrows in image to the right show cable tie location*)
- Allow for a loop of airline length between the last anchor point on the upper arm and the gripper as shown
- Route air lines behind rear side of robot, then thru hole below pedestal and attach to the Controller Panel, as shown on the following pages



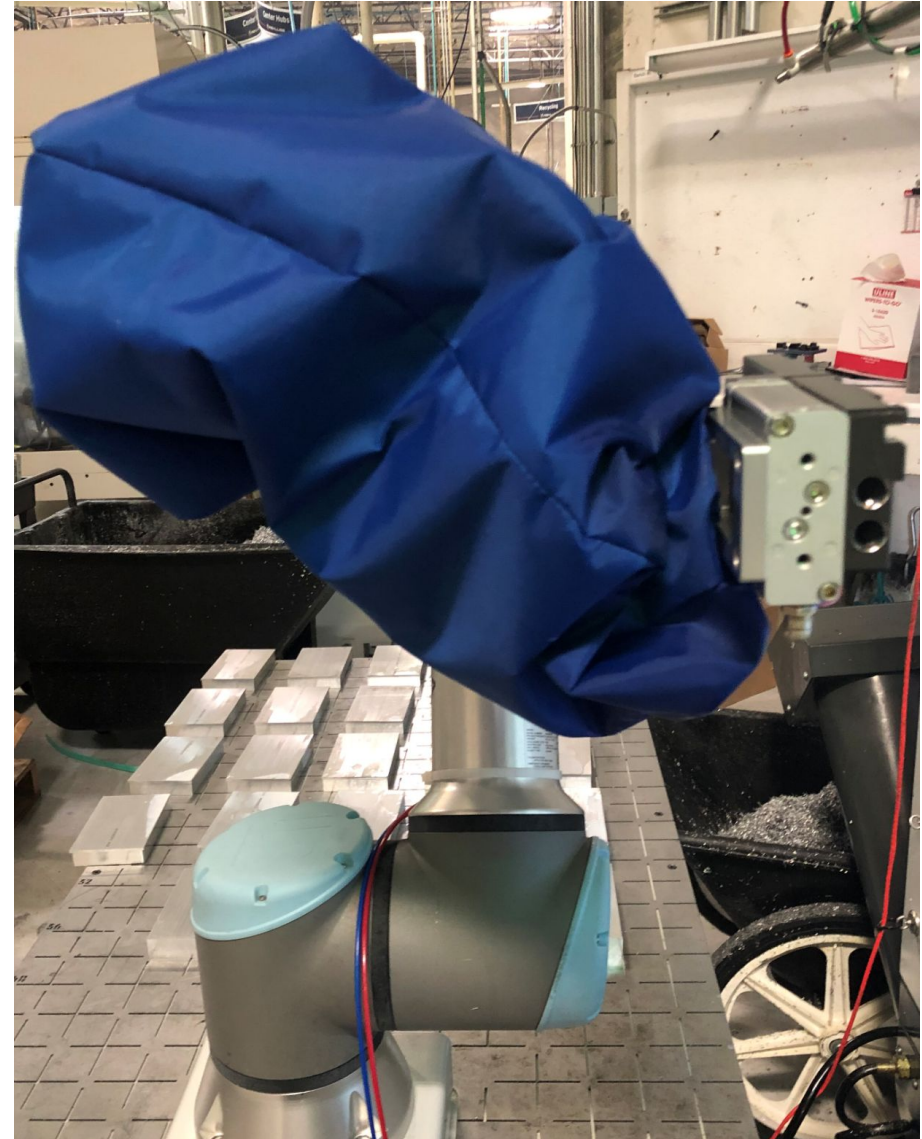
Route MultiGrip FJ Gripper Air Lines

- Using two sets of pliers, tighten each cable tie by pulling on the end of the cable tie with one pair of pliers while pushing on the locking mechanism with the other pliers
- The air lines should be slightly compressed by the cable ties
- Connect air lines from VersaBuilt System Controller (VSC) to gripper air lines with 5/32" union fittings, supplied in 5008790 - Mill Automation Tubing Kit



Installation of Robot Arm Protective Sleeve

- The Mill Automation Kit includes P/N 5009824, Protective Sleeve for 1300mm Reach Collaborative Robots.
- The sleeve will act as a deterrent against coolant and chip build up on the robot body and robot joints.
- The sleeve is 55" long with elastic, open ends. One end is slightly larger than the other. Slide the larger opening over the MultiGrip FJ Gripper (when in the closed position) and route the sleeve to the 3-axis joint. See image to the right and on the following page.
- The sleeve can be taken on and off with the gripper in place.
- To clean, remove from robot arm, rinse with water and wipe dry, then place back on robot arm.



Installation of Robot Arm Protective Sleeve



Network Configuration and Remote Mode

Section 3

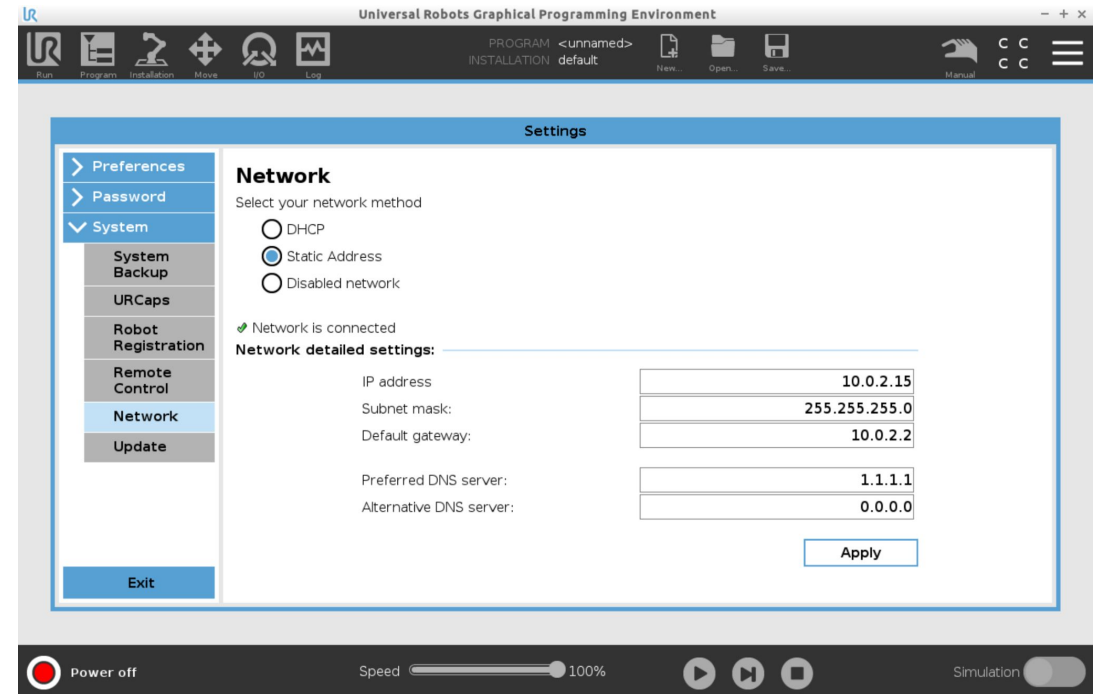
UR10e Network Settings

Navigate to the Settings page by clicking on the “Hamburger” menu (three horizontal bars in the upper right corner of the screen), then selecting System, then Network.

Select **Static Address** for the network method.
Enter the following Network detailed settings:

IP Address: 192.168.2.2
Subnet Mask: 255.255.255.0
Default Gateway: 192.168.2.1
Preferred DNS Server: 8.8.8.8
Alternate DNS Server: 0.0.0.0

Press the **Apply** button to save the changes.



Enable Remote Control

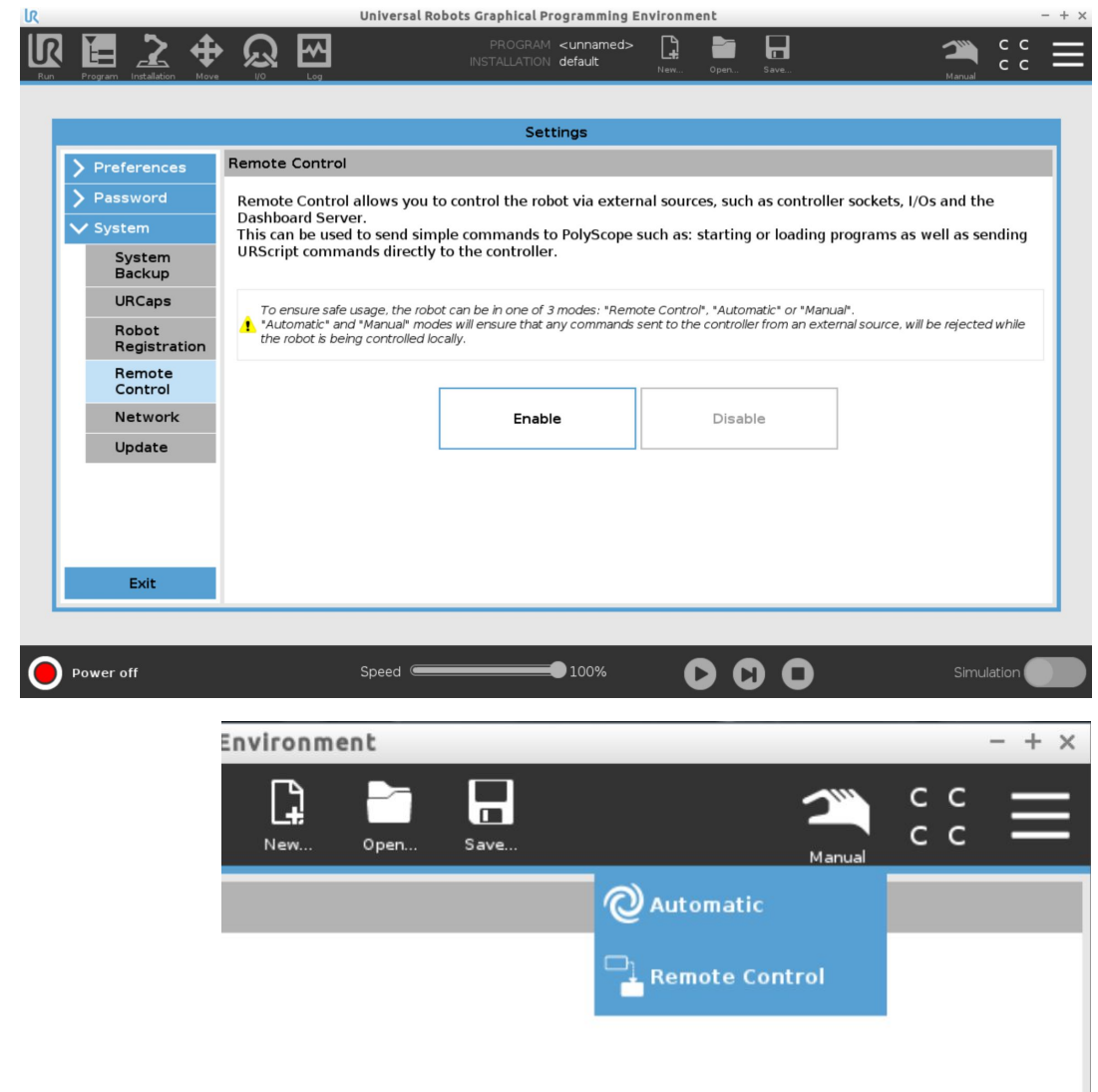
Enable Remote Control Option

Navigate to the Settings page by clicking on the “Hamburger” menu (three horizontal bars in the upper right corner of the screen), then selecting System, then Remote Control.

Press the **Enable** button to enable *the option* to put the UR robot into remote control mode.

Enable Remote Control by the VSC

When the Remote Control option is enabled, an icon will appear next to the safety checksum. Click on the icon and select the **Remote Control** option to allow the VSC to control the robot. To shift control back to the UR robot teach pendant, click on the icon and select Manual or Automatic mode.



Entering and Exiting Freedrive Mode

Section 4

UR10e Freedrive Mode

Freedrive Pop-up Menu

Calibration of the VersaCart table and the vises requires the robot to be placed into Freedrive mode. Additionally, Freedrive mode is sometimes useful when recovering from collision errors. The Enable Freedrive button is also available in the Extended Recovery panel.

After pressing the Enable Freedrive button a popup will appear. Select the jaws the robot is holding from the drop-down menu and if the robot is also holding a part, the part weight. If the robot is holding the Calibration Plate, select the Calibration Plate from the drop-down jaw menu.

Exiting Freedrive Mode

When finished with Freedrive mode, press the Stop Program or Continue button on the **UR Teach Pendant** to properly exit Freedrive mode. **Don't dismiss the pop-up message on the VSC.** The pop-up message will disappear after the Stop Program button is pressed on the UR Teach Pendant.

UR Calibration

Utility Functions

Robot Warmup

Warmup

Freedrive

Enable Freedrive

Run Table Load

Table Load

Freedrive

☐ Jaws

☒ Jaws and Part

☐ Empty Gripper

Part Weight (Pounds)

3

Jaws

Universal OP1 Jaws

☐ Custom Jaw Weight

Enable Freedrive

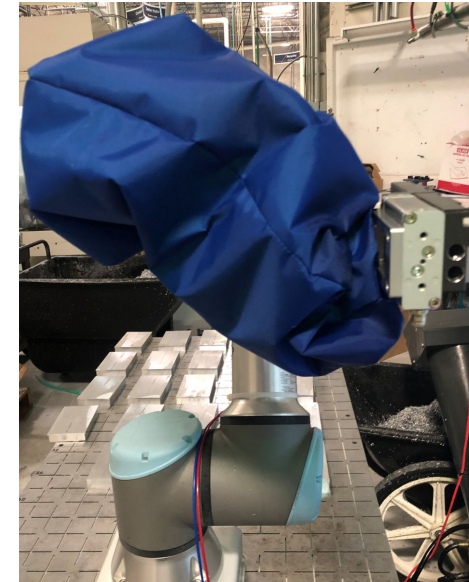
Appendices

Cleaning and Maintenance

Weekly Maintenance

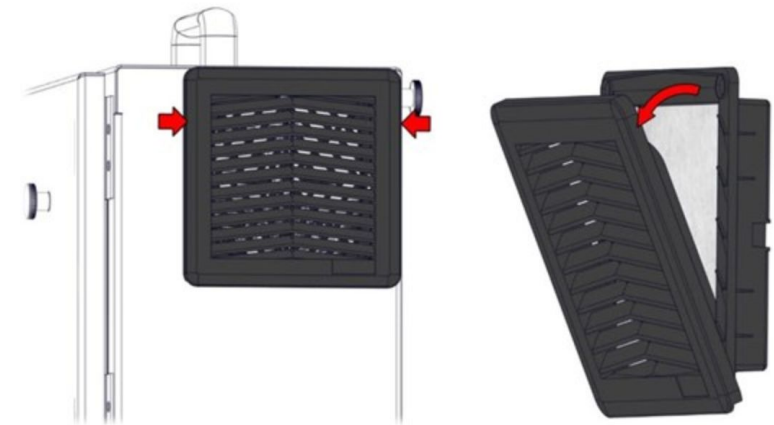
Remove the Protective Sleeve from the robot arm and rinse with warm water and dry. Using a clean damp cloth, wipe down robot arm and gripper removing any oil or chips.

Reinstall the Protective Sleeve after both the robot and Protective Sleeve are dry.



Monthly Maintenance:

- Remove UR control cabinet air filter by pulling where the red arrows are shown
- Inspect and replace when air filter becomes visibly dirty



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